Amendments to the Claims:

The listing of claims below will replace all prior versions and listings of claims in the application:

Listing of Claims:

1. (Previously Presented):   A computer implemented method for determining the spacing of objects, the method comprising the steps of:

receiving dimension data that defines a constraint;

receiving a set of supplied spacing parameter values that indicate how to space objects relative to said constraint;

selecting a grid type from a plurality of grid types, wherein the grid type is associated with a set of grid parameters;

generating grid parameter values based on the supplied spacing parameter values and the dimension data, wherein the generated grid parameter values are associated with a subset of the set of grid parameters;

generating a set of points based on the generated grid parameter values and the supplied spacing parameter values;

mapping the set of points to the defined constraint to establish locations of the objects relative to said constraint; and

storing the established locations for the objects.

2. (Canceled)

3. (Previously Presented):   The method of Claim 1, wherein the step of selecting a grid type includes the step of selecting the grid type based on the set of supplied spacing parameter values.

4. (Previously Presented):   The method of Claim 1, wherein the step of selecting a grid type includes the step of selecting the grid type based on the defined constraint.

5. (Previously Presented):   The method of Claim 1, wherein the step of selecting a grid type includes the step of selecting the grid type based on user input that specifies a particular type of grid that is to be used.

2

522559_1

PAGE 3/15 * RCVD AT 11/27/2006 7:06:25 PM [Eastern Standard Time] * SVR:USPTO-EFXRF-6/40 * DNIS:2738300 * CSID:7136234846 * DURATION (mm-ss):03-04

6. (Previously Presented): The method of Claim 1, wherein the step of selecting a grid type includes the step of selecting the grid type based on the set of supplied spacing parameter values and the defined constraint.

7. (Canceled)

8. (Original): The method of Claim 1, further comprising the step of receiving input that specifies one or more attributes of said constraint, wherein said one or more attributes are associated with one or more bounds of one or more dimensions of said constraint.

9. (Previously Presented): The method of Claim 1, wherein the step of receiving dimension data that defines a constraint includes the step of receiving data that defines a one-dimensional constraint.

10. (Previously Presented): The method of Claim 1, wherein the step of receiving dimension data that defines a constraint includes the step of receiving data that defines a multi-dimensional constraint.

11. (Previously Presented): The method of Claim 1, wherein the step of receiving dimension data that defines a constraint includes the step of receiving data that defines a spline constraint.

12. (Previously Presented): The method of Claim 1, wherein the step of receiving dimension data that defines a constraint includes the step of receiving data that defines a sphere constraint.

13. (Previously Presented): The method of Claim 1, wherein the step of receiving dimension data that defines a constraint includes the step of receiving data that defines a cylinder constraint.

14. (Previously Presented): The method of Claim 1, wherein the step of receiving dimension data that defines a constraint includes the step of receiving data that defines a rectangle constraint.

15. (Previously Presented): The method of Claim 1, wherein the step of receiving dimension data that defines a constraint includes the step of receiving data that defines a line segment constraint.

16. (Previously Presented): The method of Claim 1, wherein the step of selecting a grid type

3

includes the step of selecting a two-dimensional grid type.

17. (Previously Presented): The method of Claim 1, wherein the step of selecting a grid type includes the step of selecting a three-dimensional grid type.

18. (Previously Presented): The method of Claim 1, wherein the step of selecting a grid type includes the step of selecting a rectangular grid type.

19. (Previously Presented): The method of Claim 1, wherein the step of selecting a grid type includes the step of selecting a polar grid type.

20. (Previously Presented): The method of Claim 1, wherein the step of selecting a grid type includes the step of selecting a hex grid type.

21. (Previously Presented): The method of Claim 1, wherein the step of selecting a grid type includes the step of selecting a triangular mesh grid type.

22. (Previously Presented): The method of Claim 1, wherein the step of selecting a grid type includes the step of selecting a spherical grid type.

23. (Previously Presented): The method of Claim 1, wherein the step of selecting a grid type includes the step of selecting a random grid type.

24. (Previously Presented): The method of Claim 1, wherein the step of selecting a grid type includes the step of selecting a scattered grid type.

25. (Original): The method of Claim 1, further comprising the step of receiving a set of object information, wherein the set of object information identifies a particular object to be placed on the constraint at locations based on said generated set of points.

26. (Original): The method of Claim 25, wherein the step of generating the set of grid points includes the steps of generating the set of grid points based on the set of object information.

27. (Original): The method of Claim 26, wherein:
      the set of object information identifies a bounding box that is associated with the
           particular object; and

4

the step of generating the set of grid points based on the set of object information

comprises the step of generating the set of grid points based the bounding box.

28. (Previously Presented):   The method of Claim 1, wherein the step of mapping the set of points to the defined constraint includes the step of determining one or more locations to place objects on said constraint by identifying one or more areas of said grid that intersect said constraint.

29. (Original):   The method of Claim 28, further comprising the step of:
receiving pivot point information, wherein the pivot point information specifies pivot points for the placement of objects relative to the generated set of points; and
placing objects on said constraint such that the pivot points of said objects coincide with said one or more locations.

30. (Original):   The method of Claim 28, further comprises the steps of:
identifying a particular object;
generating a copy of said particular object; and
placing the copy of said particular object at one or more of said one or more locations.

31. (Original):   The method of Claim 28, further comprises the steps of:
identifying a particular object;
generating an instance of said particular object; and
placing the instance of said particular object at one or more of said one or more locations.

32. (Currently Amended):   A ~~tangible~~ computer-readable medium storage carrying one or more sequences of instructions for determining the spacing of objects, wherein execution of the one or more sequences of instructions by one or more processors causes the one or more processors to perform the steps of:
receiving dimension data that defines a constraint;
receiving a set of supplied spacing parameter values that indicate how to space objects
relative to said constraint;
selecting a grid type from a plurality of grid types, wherein the grid type is associated
with a set of grid parameters;
generating grid parameter values based on the supplied spacing parameter values and the

5

622559_1

PAGE 6/15 * RCVD AT 11/27/2006 7:06:25 PM [Eastern Standard Time] * SVR:USPTO-EFXRF-6/40 * DNIS:2738300 * CSID:7136234846 * DURATION (mm-ss):03-04

dimension data, wherein the generated grid parameter values are associated with a

subset of the set of grid parameters;

generating a set of points based on the generated grid parameter values and the supplied

spacing parameter values;

mapping the set of points to the defined constraint to establish locations of the objects

relative to said constraint; and

storing the established locations for the objects.

33. (Canceled)

34. (Currently Amended):   The computer-readable storage medium of Claim 32, wherein the step of selecting a grid type includes the step of selecting the grid type based on the set of supplied spacing parameter values.

35. (Currently Amended):   The computer-readable storage medium of Claim 32, wherein the step of selecting a grid type includes the step of selecting the grid type based on the defined constraint.

36. (Currently Amended):   The computer-readable storage medium of Claim 32, wherein the step of selecting a grid type includes the step of selecting the grid type based on user input that specifies a particular type of grid that is to be used.

37. (Currently Amended):   The computer-readable storage medium of Claim 32, wherein the step of selecting a grid type includes the step of selecting the grid type based on the set of supplied spacing parameter values and the defined constraint.

38. (Canceled)

39. (Currently Amended):   The computer-readable medium storage of Claim 32, further comprising instructions for performing the step of receiving input that specifies one or more attributes of said constraint, wherein said one or more attributes are associated with one or more bounds of one or more dimensions of said constraint.

40. (Currently Amended):   The computer-readable storage medium of Claim 32, wherein the step of receiving dimension data that defines a constraint includes the step of receiving data that

6

defines a one-dimensional constraint.

41. (Currently Amended): The computer-readable storage medium of Claim 32, wherein the step of receiving dimension data that defines a constraint includes the step of receiving data that defines a multi-dimensional constraint.

42. (Currently Amended): The computer-readable storage medium of Claim 32, wherein the step of selecting a grid type includes the step of selecting a two-dimensional grid type.

43. (Currently Amended): The computer-readable storage medium of Claim 32, wherein the step of selecting a grid type includes the step of selecting a three-dimensional grid type.

44. (Currently Amended): The computer-readable storage medium of Claim 32, wherein the step of selecting a grid type includes the step of selecting a rectangular grid type.

45. (Currently Amended): The computer-readable storage medium of Claim 32, wherein the step of selecting a grid type includes the step of selecting a polar grid type.

46. (Currently Amended): The computer-readable storage medium of Claim 32, wherein the step of selecting a grid type includes the step of selecting a triangular mesh grid type.

47. (Currently Amended): The computer-readable storage medium of Claim 32, wherein the step of selecting a grid type includes the step of selecting a spherical grid type.

48. (Currently Amended): The computer-readable storage medium of Claim 32, further comprising instructions for performing the step of receiving a set of object information, wherein the set of object information identifies a particular object to be placed on the constraint at locations based on said generated set of points.

49. (Currently Amended): The computer-readable storage medium of Claim 48, wherein the step of generating the set of grid points includes the steps of generating the set of grid points based on the set of object information.

50. (Currently Amended): The computer-readable storage medium of Claim 49, wherein:

the set of object information identifies a bounding box that is associated with the particular object; and

7

the step of generating the set of grid points based on the set of object information comprises the step of generating the set of grid points based the bounding box.

51. (Currently Amended): The computer-readable storage medium of Claim 32, wherein the step of mapping the set of points to the defined constraint includes the step of determining one or more locations to place objects on said constraint by identifying one or more areas of said grid that intersect said constraint.

52. (Currently Amended): The computer-readable storage medium of Claim 51, further comprising instructions for performing the step of:

receiving pivot point information, wherein the pivot point information specifies pivot points for the placement of objects relative to the generated set of points; and

placing objects on said constraint such that the pivot points of said objects coincide with said one or more locations.

53. (Currently Amended): The computer-readable storage medium of Claim 51, further comprising instructions for performing the steps of:

identifying a particular object;

generating a copy of said particular object; and

placing the copy of said particular object at one or more of said one or more locations.

54. (Currently Amended): The computer-readable storage medium of Claim 51, further comprising instructions for performing the steps of:

identifying a particular object;

generating an instance of said particular object; and

placing the instance of said particular object at one or more of said one or more locations.

55. (Previously Presented): A computer system for determining the spacing of objects, the system comprising:

a memory;

one or more processors coupled to the memory; and

a set of computer instructions contained in the memory, the set of computer instruction including computer instructions which when executed by the one or more processors, cause the one or more processors to perform the steps of:

8

522559_1

receiving dimension data that defines a constraint;

receiving a set of supplied spacing parameter values that indicate how to
space objects relative to said constraint;

selecting a grid type from a plurality of grid types, wherein the grid type is
associated with a set of grid parameters;

generating grid parameter values based on the supplied spacing parameter
values and the dimension data, wherein the generated grid
parameter values are associated with a subset of the set of grid
parameters;

generating a set of points based on the generated grid parameter values
and the supplied spacing parameter values;

mapping the set of points to the defined constraint to establish
locations of the objects relative to said constraint; and

storing the established locations for the objects.

56. (Canceled)

57. (Previously Presented):   A computer system for determining the spacing of objects, the
system comprising:

means for receiving dimension data that defines a constraint;

means for receiving a set of supplied spacing parameter values that indicate how to space
objects relative to said constraint;

means for selecting a grid type from a plurality of grid types, wherein the grid type is
associated with a set of grid parameters;

means for generating grid parameter values based on the supplied spacing parameter
values and the dimension data, wherein the generated grid parameter values are
associated with a subset of the set of grid parameters;

means for generating a set of points based on the generated grid parameter values and the
supplied spacing parameter values;

means for mapping the set of points to the defined constraint to establish locations of the
objects relative to said constraint; and

means for storing the established locations for the objects.

58-62. (Canceled)

63. (Currently Amended):   A ~~tangible~~ computer-readable <u>storage</u> medium carrying one or more sequences of instructions for determining the spacing of objects, wherein execution of the one or more sequences of instructions by one or more processors causes the one or more processors to perform the steps of:

    receiving dimension data that defines a constraint;

    receiving a set of supplied spacing parameter values that indicate how to space objects relative to said constraint;

    selecting a grid type from a plurality of grid types, wherein the grid type is associated with a set of grid parameters;

    generating grid parameter values based on the supplied spacing parameter values and the dimension data, wherein the generated grid parameter values are associated with a subset of the set of grid parameters;

    generating a set of points based on the generated grid parameter values and the supplied spacing parameter values;

    mapping the set of points to the defined constraint to establish locations of the objects relative to said constraint; and

    displaying the <u>objects on said constraint at the</u> established locations for the objects.

10

522559_1